



# *Bar Elements*

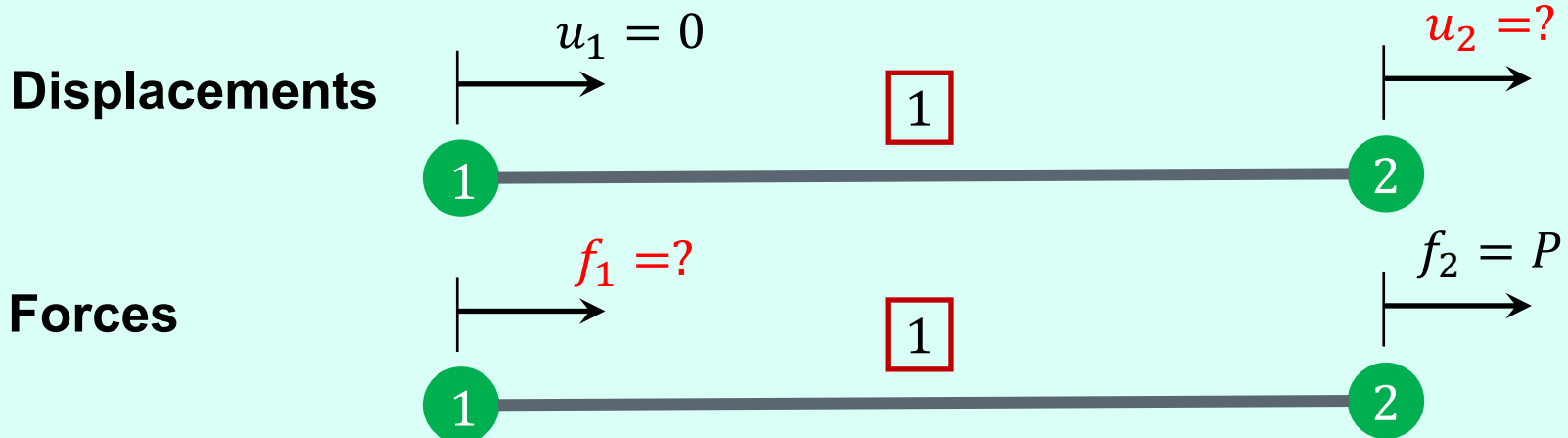
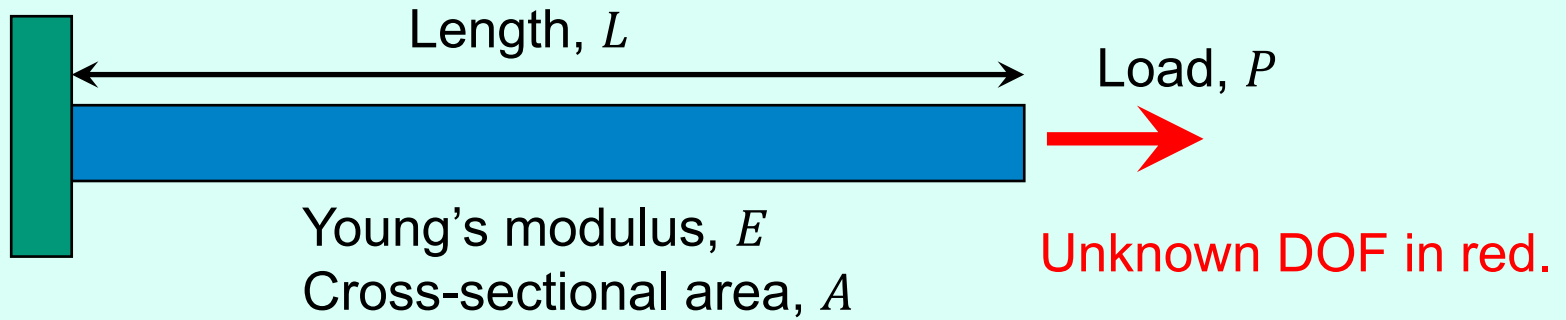
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*EG3111 - Finite Element Analysis and Design*

### 3b. Bar Element Example 1



In general, either the displacement OR the force at a node is known, but never NEITHER or BOTH.

$$\underline{d} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ u_2 \end{bmatrix} \quad \underline{f} = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} = \begin{bmatrix} f_1 \\ P \end{bmatrix}$$

## 3b. Bar Element Example 1

All that is needed is the elemental stiffness matrix.

**For element (1)**

$$[k^{(1)}] = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \quad \underline{d}^{(1)} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

As only one element the elemental matrix is the same as the global matrix so no “assembly” required.

$$[K] = [k^{(1)}] = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\boxed{[K] \cdot \underline{d} = \underline{f}} \quad \Rightarrow \quad \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ u_2 \end{bmatrix} = \begin{bmatrix} f_1 \\ P \end{bmatrix}$$

## 3b. Bar Element Example 1

Two equations for 2 unknowns ( $u_2$  and  $f_1$ )

$$\frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ u_2 \end{bmatrix} = \begin{bmatrix} f_1 \\ P \end{bmatrix}$$

$$\frac{EA}{L} (1 \times 0 - 1 \times u_2) = f_1 \quad \boxed{\text{Eq 1}}$$

$$\frac{EA}{L} (-1 \times 0 + 1 \times u_2) = P \quad \boxed{\text{Eq 2}}$$



## 3b. Bar Element Example 1

Second equation gives

$$\frac{EA}{L} (-1 \times 0 + 1 \times u_2) = P \quad \xRightarrow{\text{Partition}} \quad \frac{EA}{L} u_2 = P$$

$$u_2 = \frac{PL}{EA} \quad \leftarrow \quad \text{Same as previous solution as same linear shape function}$$

First equation gives

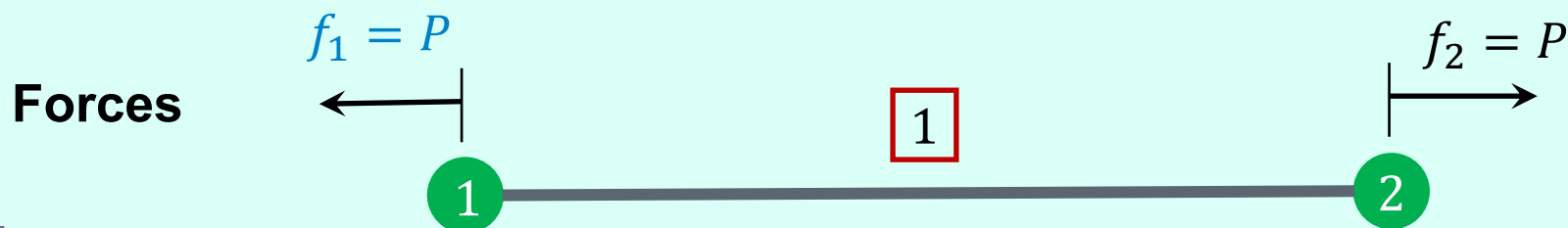
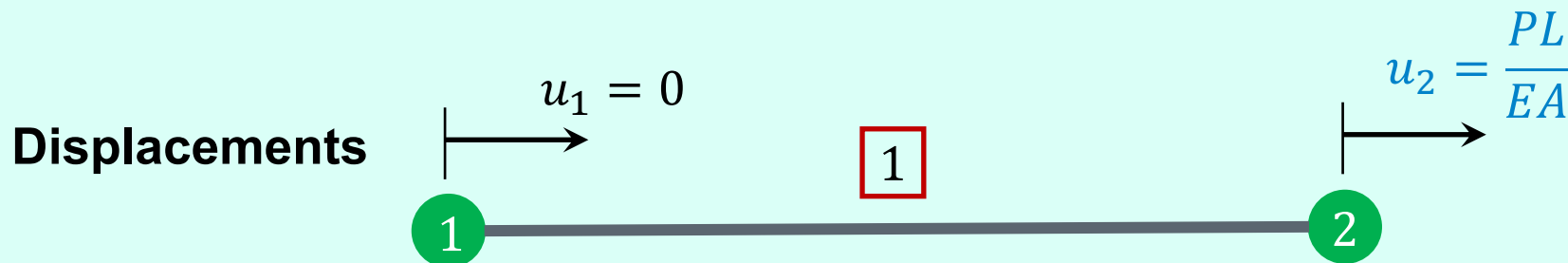
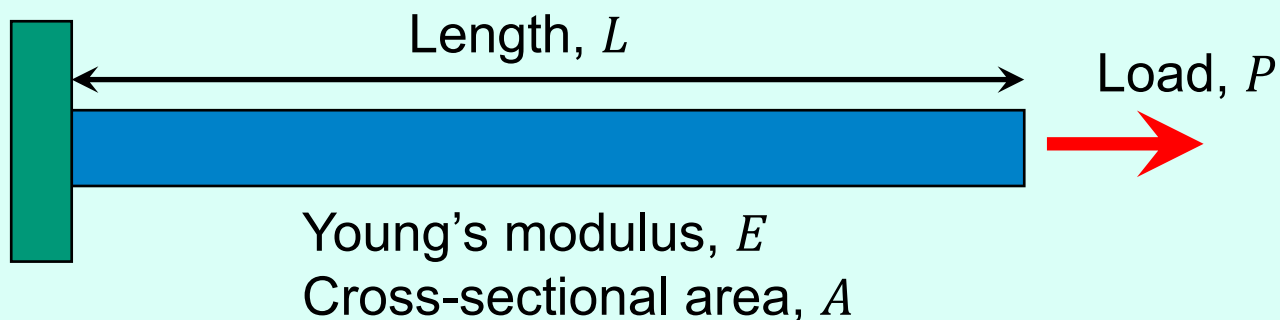
$$\frac{EA}{L} (1 \times 0 - 1 \times u_2) = f_1 \quad \Rightarrow \quad -\frac{EA}{L} u_2 = f_1$$

Substitute  $u_2$  in Eq 1

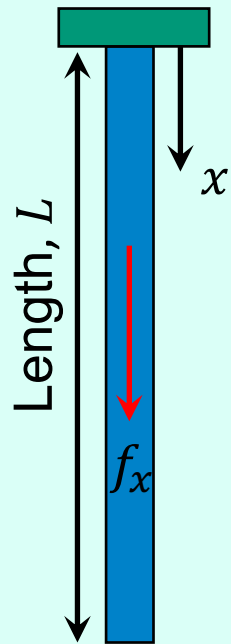
$$f_1 = -P \quad \leftarrow$$

This is the reaction force provided by the wall to keep the displacement  $u_1 = 0$ .

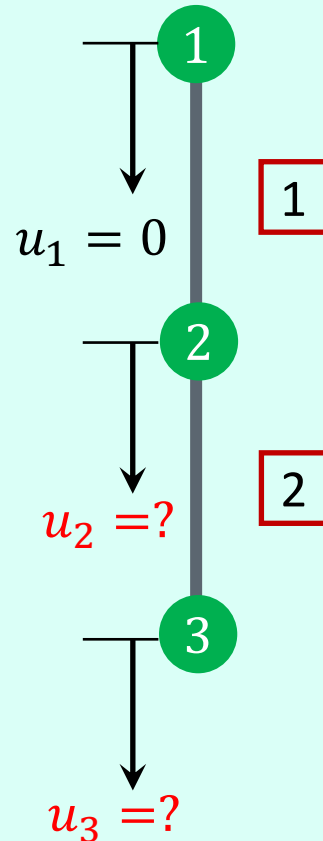
### 3b. Bar Element Example 1



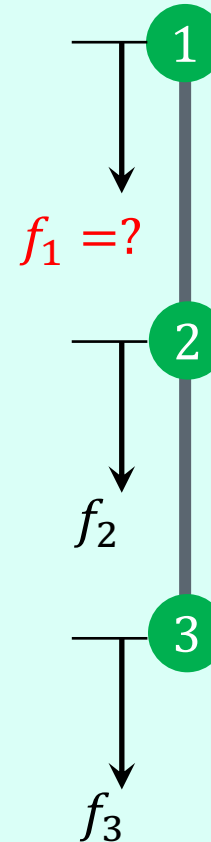
## 3b. Bar Element Example 2 : Self weight



**Displacements**



**Forces**



Body force:  $f_x = \rho g$

From section 2b, we know exact solution is a quadratic.

Here we use two linear bar elements to get an approximate solution.

## 3b. Bar Element Example 2 : Self weight

### Forces due to distributed load

$$\Omega^e = - \int_{V^e} f_x u(x) dx = -AL^e \int_0^1 \rho g \cdot \underline{n}^{eT}(\xi) d\xi \cdot \underline{d}^e = -\underline{f}^{eT} \cdot \underline{d}^e$$

So

$$\underline{f}^e = AL^e \rho g \int_0^1 \underline{n}^e(\xi) d\xi = AL^e \rho g \int_0^1 \begin{bmatrix} 1 - \xi \\ \xi \end{bmatrix} d\xi = AL^e \rho g \begin{bmatrix} \xi - \frac{1}{2}\xi^2 \\ \frac{1}{2}\xi^2 \end{bmatrix}_0^1$$

$$\underline{f}^e = AL^e \rho g \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix} = \frac{AL^e \rho g}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Where  $L^e = \frac{L}{2}$  Each element is half the total length  $L$



## 3b. Bar Element Example 2 : Self weight

### Global matrices

$$\underline{d} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 0 \\ u_2 \\ u_3 \end{bmatrix}$$

$$\underline{f} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix}$$

### Elemental stiffness matrices

*Element (1)*

$$[k^{(1)}] = \frac{EA}{\frac{1}{2}L} \begin{bmatrix} u_1 & u_2 \\ 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{matrix} u_1 \\ u_2 \end{matrix}$$

$$\underline{d}^{(1)} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

Force due to unknown reaction at node 1

Applied load due to self weight

$$\underline{f}^{(1)} = \frac{A \frac{L}{2} \rho g}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} f_1 \\ f_2 \end{bmatrix} = \frac{AL\rho g}{4} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} f_1 \\ 0 \end{bmatrix}$$

## 3b. Bar Element Example 2 : Self weight

*Element (2)*

$$[k^{(2)}] = \frac{EA}{\frac{1}{2}L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{matrix} u_2 \\ u_3 \end{matrix} \quad \underline{d}^{(2)} = \begin{bmatrix} u_2 \\ u_3 \end{bmatrix}$$

$$\underline{f}^{(2)} = \frac{AL\rho g}{4} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} f_2 \\ f_3 \end{bmatrix} = \frac{AL\rho g}{4} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$a = \frac{AL\rho g}{4}$$

## 3b. Bar Element Example 2 : Self weight

### Assembly of elemental force matrices

$$\underline{f} = \begin{bmatrix} a + f_1 \\ a + a \\ a \end{bmatrix} \begin{matrix} u_1 \\ u_2 \\ u_3 \end{matrix}$$

#### *Element (1)*

$$\underline{f}^{(1)} = a \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} f_1 \\ 0 \end{bmatrix} \begin{matrix} u_1 \\ u_2 \end{matrix}$$

#### *Element (2)*

$$\underline{f}^{(2)} = a \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{matrix} u_2 \\ u_3 \end{matrix}$$

## 3b. Bar Element Example 2 : Self weight

### Global stiffness matrix

$$[K] = \frac{2EA}{L} \begin{bmatrix} u_1 & u_2 & u_3 \\ 1 & -1 & 0 \\ -1 & 1+1 & -1 \\ 0 & -1 & 1 \end{bmatrix} \begin{matrix} u_1 \\ u_2 \\ u_3 \end{matrix}$$

### Element (1)

$$[k^{(1)}] = \frac{2EA}{L} \begin{bmatrix} u_1 & u_2 \\ 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{matrix} u_1 \\ u_2 \end{matrix}$$

### Element (2)

$$[k^{(2)}] = \frac{2EA}{L} \begin{bmatrix} u_2 & u_3 \\ 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{matrix} u_2 \\ u_3 \end{matrix}$$

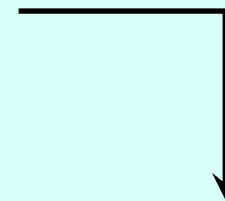
### 3b. Bar Element Example 2 : Self weight

$$[K] \cdot \underline{d} = \underline{f} \Rightarrow \frac{2EA}{L} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} a + f_1 \\ 2a \\ a \end{bmatrix} \quad \text{Eq 3}$$

$$a = \frac{AL\rho g}{4}$$

As in previous example, partition out 2<sup>nd</sup> and 3<sup>rd</sup> equations where forces are known

$$\frac{2EA}{L} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 2a \\ a \end{bmatrix}$$



#### Matrix inversion (reminder)

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{(ad - bc)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\begin{bmatrix} u_2 \\ u_3 \end{bmatrix} = \frac{La}{2EA} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

### 3b. Bar Element Example 2 : Self weight

$$\begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}^{-1} = \frac{1}{(2 \times 1 - (-1)^2)} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \frac{1}{2-1} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

$a$  ↘

$$\begin{bmatrix} u_2 \\ u_3 \end{bmatrix} = \frac{L}{2EA} \times \frac{AL\rho g}{4} \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \frac{L^2\rho g}{8E} \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

First equation from Eq 3 then gives

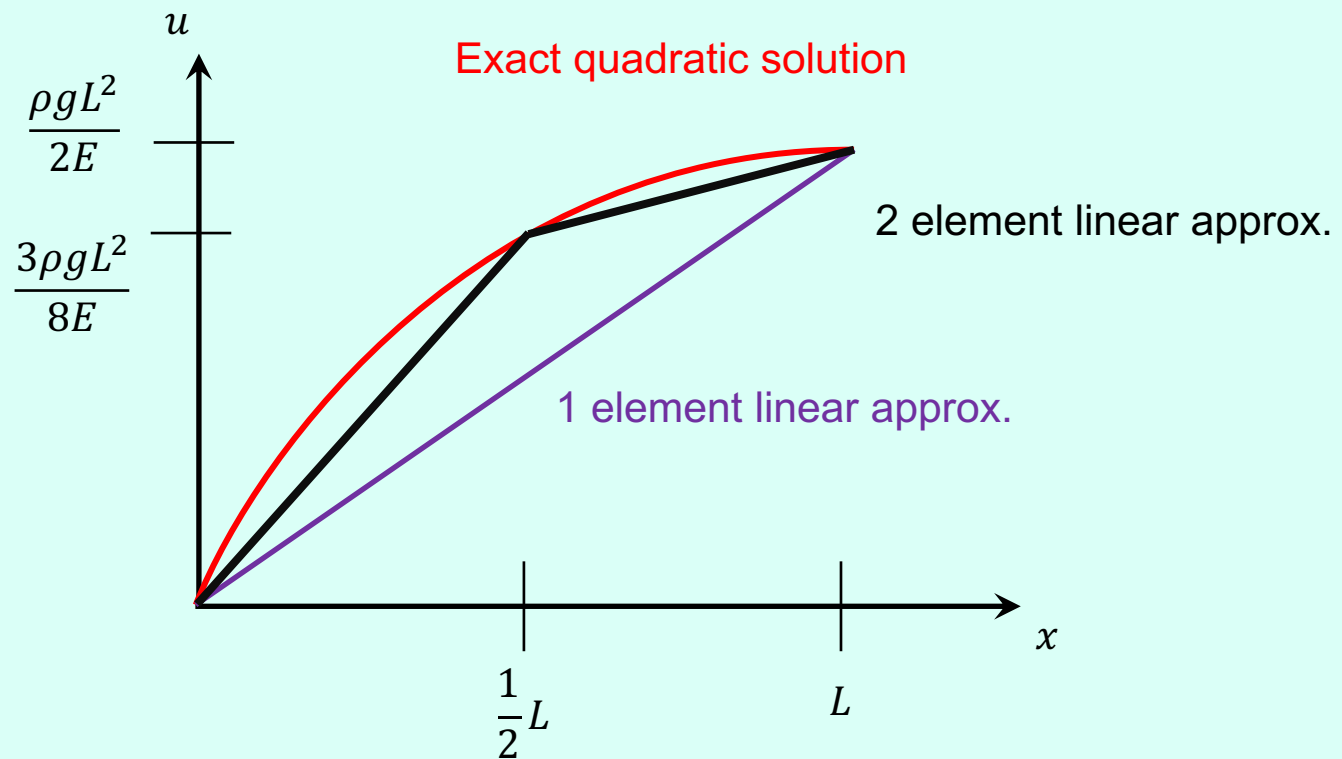
$$\frac{2EA}{L} [1 \cdot (0) - 1 \cdot (u_2) \cdot 0(u_3)] = a + f_1$$

$$\Rightarrow a + f_1 = \frac{2EA}{L} (-u_2) = -\frac{2EA}{L} \cdot \frac{3L^2\rho g}{8E} = -\frac{3AL\rho g}{4}$$

$$\Rightarrow f_1 = -\frac{3AL\rho g}{4} - \frac{AL\rho g}{4} = -AL\rho g \left( \frac{3}{4} + \frac{1}{4} \right) \Rightarrow \boxed{f_1 = -AL\rho g}$$

**Reaction = weight of bar**

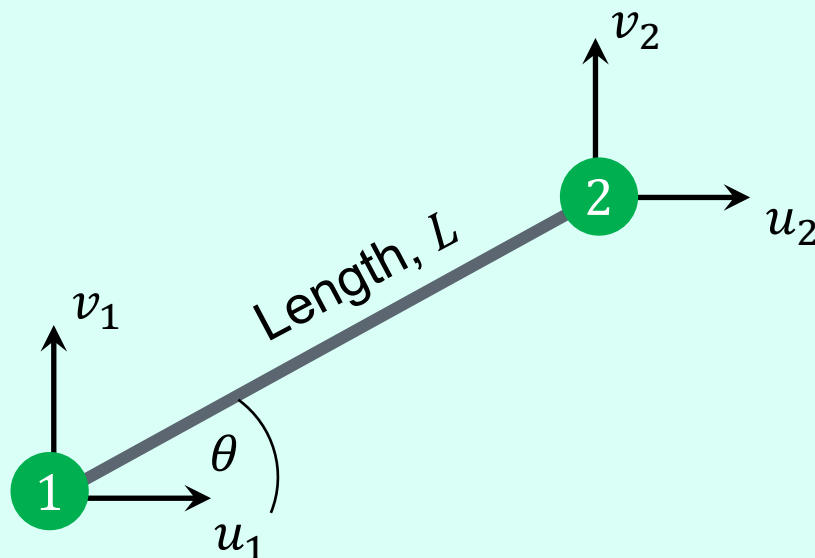
## 3b. Bar Element Example 2 : Self weight



### 3c. Bar elements for 2D frameworks

Consider a bar element with orientation  $\theta$ . In 2D the horizontal and vertical displacements are  $u$  and  $v$ .

**DOF**



Only displacements parallel to bar axis cause extension/compression

